





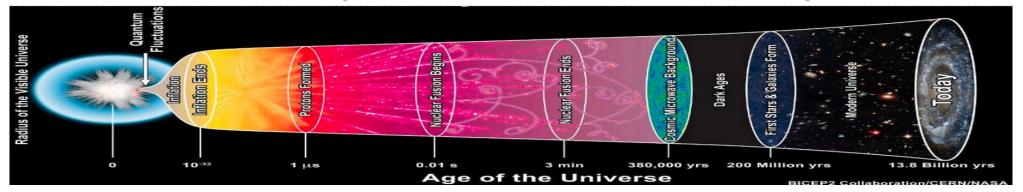


- 1 Introduction
- 2 Data generation
- 3 Data analysis
- 4 Future improvements



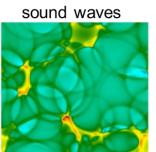
1 Introduction

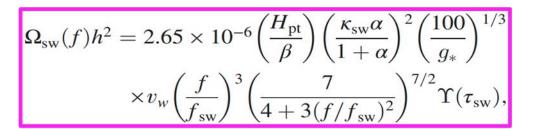
SWs dominated GWs production: Nucleation, Expansion, Percolation



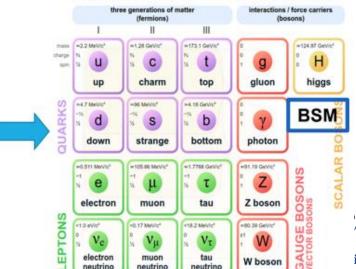
Energy density Spectrum

$$\Omega_{\rm GW}(f) = \frac{d\rho_{\rm GW}}{\rho_c d \log f}$$





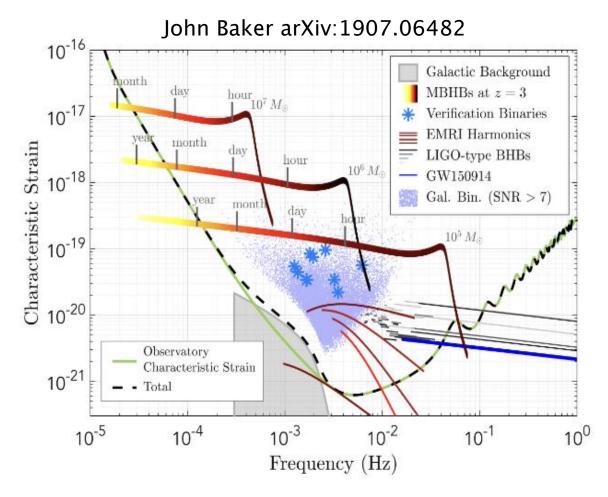
Standard Model of Elementary Particles





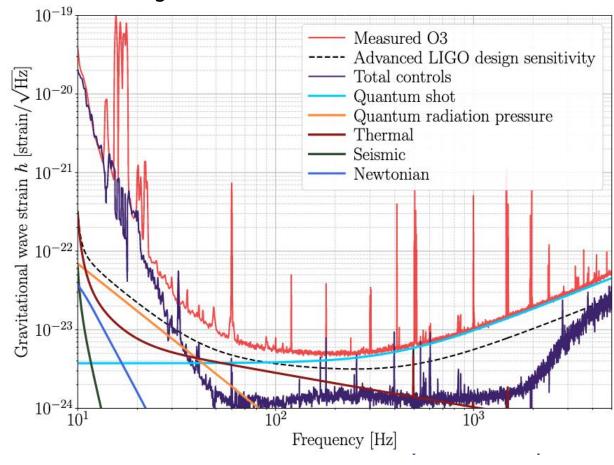
1 Introduction

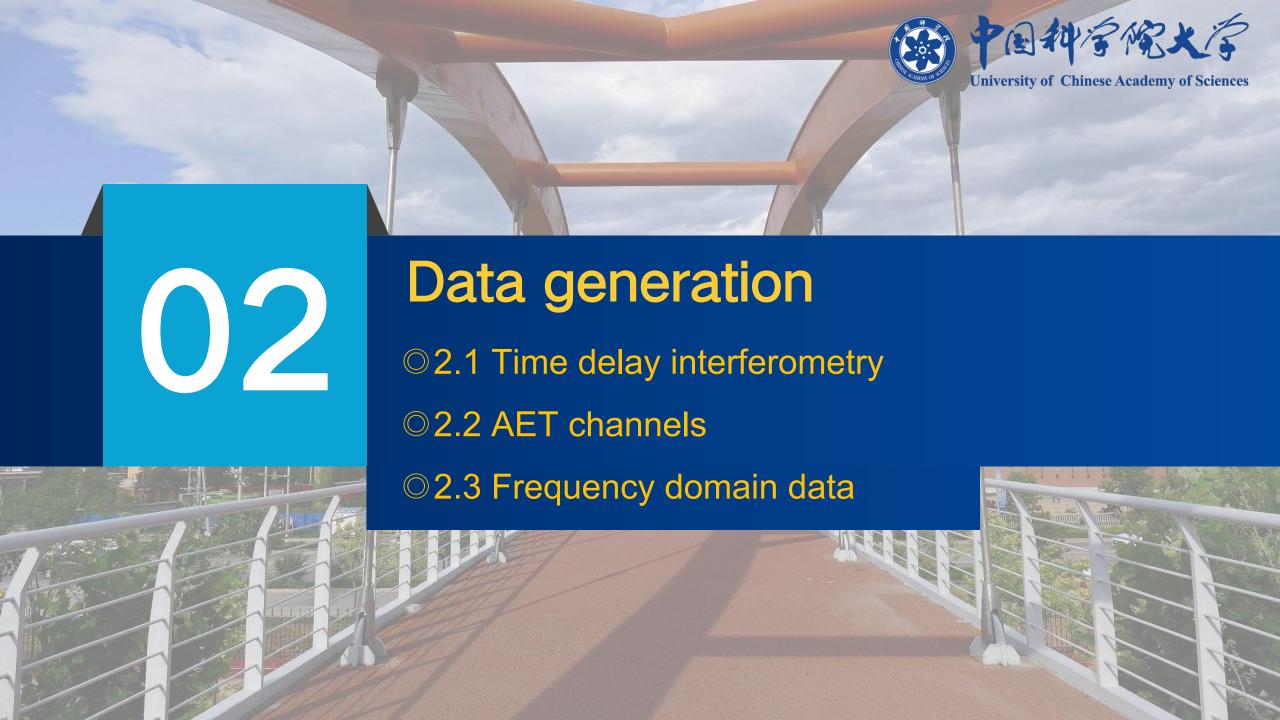
Space-based GWs detectors Miliherze range



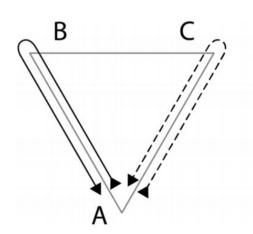
Ground-based GWs detectors Handred Hertz range

Craig Cahillane arXiv:2202.00847





2.1 Time delay interferometry (TDI)



phase difference at vertex A

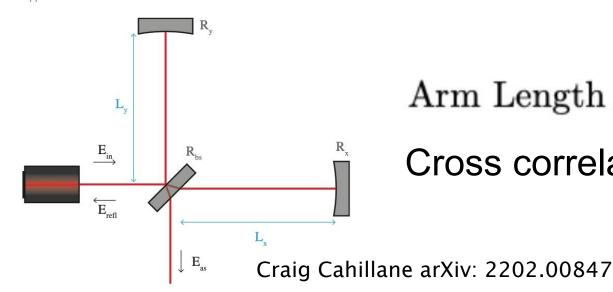
$$\Phi_{A_{BC}}(t) = \Delta \varphi_{A_{BC}}(t) + n_{A_{BC}}(t) < \infty$$

noise at vertex A

Arm Length $L = 2.5 \times 10^9 \ m$

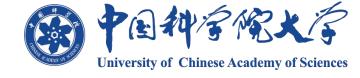
TDI (cancel laser frequency noise)

Tristan L. Smith arXiv: 1908.00546



Arm Length $L = 4 \ km$

Cross correlation method for LIGO



2.2 AET channels

XYZ channels

Vertex A: X

Vertex B:Y

Vertex C: Z

AET channels

$$A = \frac{1}{\sqrt{2}}(Z - X)$$

$$E = \frac{1}{\sqrt{6}}(X - 2Y + Z)$$

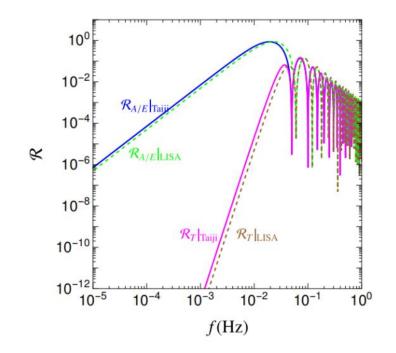
$$T = \frac{1}{\sqrt{3}}(X + Y + Z)$$

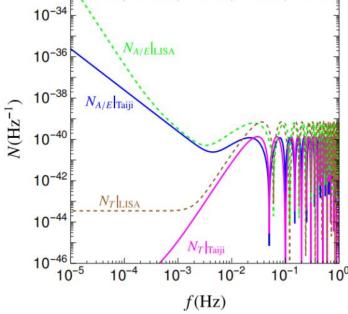
Power spectral densities

$$PSD_A(f) = S_h(f)\mathcal{R}_A(f) + N_A(f)$$

$$PSD_E(f) = S_h(f)\mathcal{R}_E(f) + N_E(f)$$

$$PSD_T(f) = S_h(f)\mathcal{R}_T(f) + N_T(f)$$





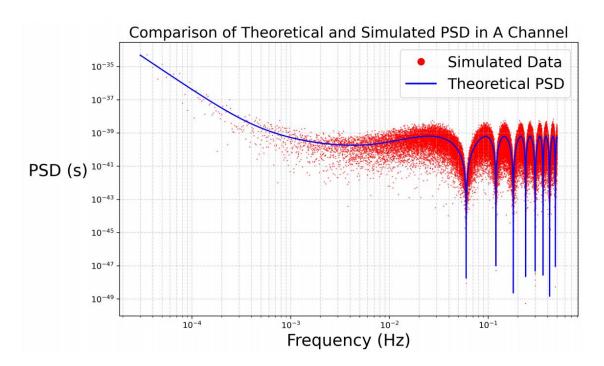
Null channel method $PSD_T(f) = N_T(f)$

Tristan L. Smith arXiv: 1908.00546

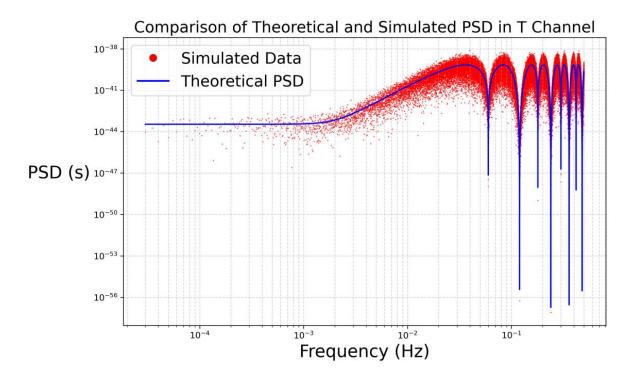


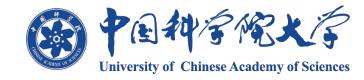
2.3 Frequency domain data

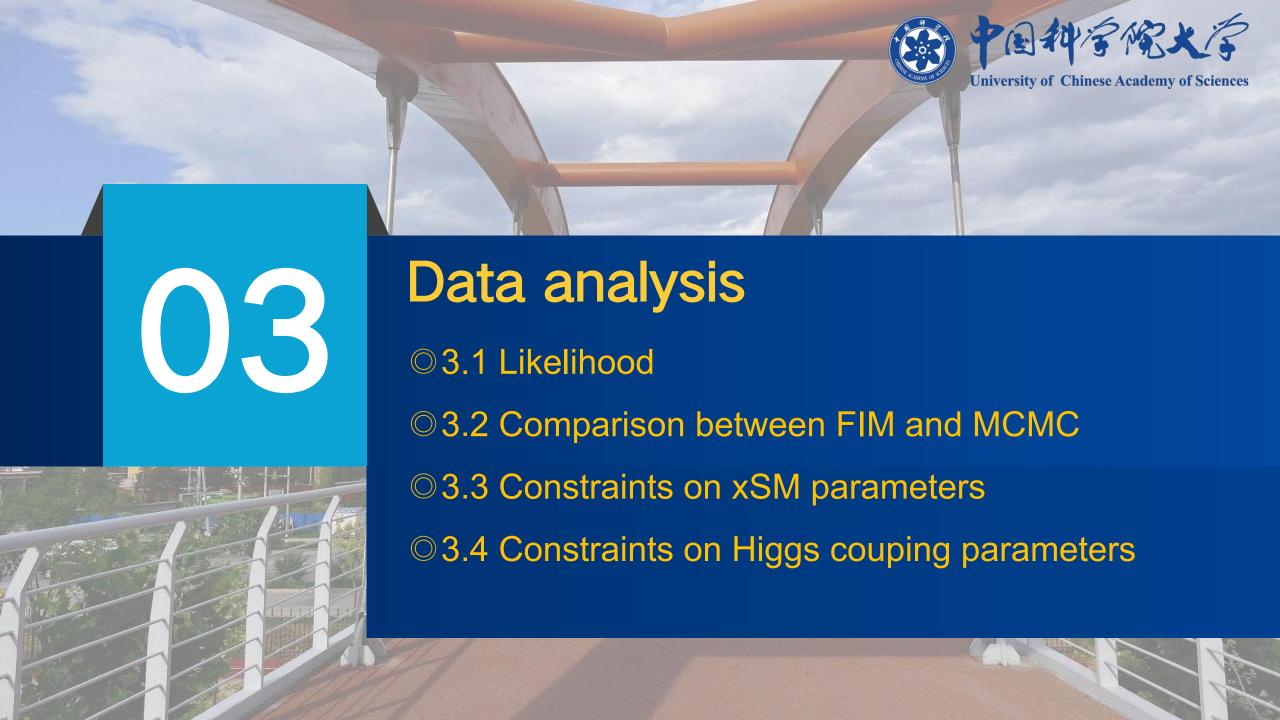
Distribution
$$P\left(\tilde{d}_a(f_k)\right) = \frac{1}{2\pi\sigma_a^2} \exp\left[-\frac{\left|\tilde{d}_a(f_k)\right|^2}{2\sigma_a^2}\right]$$
 $\sigma_a^2 = \frac{Tf_s^2}{4}P_a(f_k)$



Generate in frequency domain







3.1 Likelihood

Logarithmic Likelihood function

$$\ln \mathcal{L} = -\sum_{\kappa=1}^{N_0} \sum_{k=1}^{N/2} \left\{ \ln \frac{\pi^3 T^3 f_s^6 \left[S_A(f_k) + N_A(f_k) \right] \left[S_E(f_k) + N_E(f_k) \right] N_T(f_k)}{8} \right. \\ \left. + \frac{2}{T f_s^2} \left[\frac{\left| \tilde{d}_A^{\kappa}(f_k) \right|^2}{S_A(f_k) + N_A(f_k)} + \frac{\left| \tilde{d}_E^{\kappa}(f_k) \right|^2}{S_E(f_k) + N_E(f_k)} + \frac{\left| \tilde{d}_T^{\kappa}(f_k) \right|^2}{N_T(f_k)} \right] \right\} \frac{N}{T} = 4 \text{ years : observation time}$$

k: index of discrete frequency

 $N=10^6$: data number in one segment

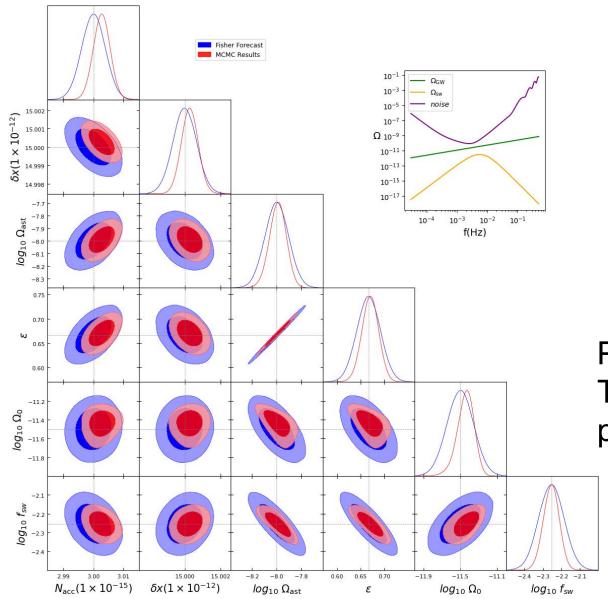
 κ : segments index

Fisher information matrix $F_{ij} = -E\left(\frac{\partial^2 \ln p(\boldsymbol{\theta})\mathcal{L}(\boldsymbol{\theta})}{\partial \theta \cdot \partial \theta}\right)$

$$F_{ij}^{\text{likelihood}} = N_0 \sum_{k=0}^{N/2} \left[\frac{2}{[S_A(f_k) + N_A(f_k)]^2} \frac{\partial [S_A(f_k) + N_A(f_k)]}{\partial \theta_i} \frac{\partial [S_A(f_k) + N_A(f_k)]}{\partial \theta_j} + \frac{1}{N_T^2(f_k)} \frac{\partial N_T(f_k)}{\partial \theta_i} \frac{\partial N_T(f_k)}{\partial \theta_i} \frac{\partial N_T(f_k)}{\partial \theta_i} \right]$$



3.2 Comparison between FIM and MCMC

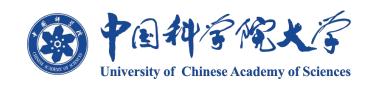


$$S_A = S_E = \frac{3H_0^2}{4\pi^2} \frac{\Omega_{\text{ast}} \left(\frac{f}{f_{\text{ref}}}\right)^{\varepsilon} + \Omega_{\text{sw}}(f)}{f^3} \mathcal{R}_A$$

$$\Omega_{\rm sw}(f) = \Omega_0 \left(\frac{f}{f_{\rm sw}}\right)^3 \left(\frac{7}{4 + 3\left(f/f_{\rm sw}\right)^2}\right)^{7/2}$$

Chiara Caprini arXiv: 2403.03723

Parameters are fully recovered
The deviation arises from the non-Gaussian
properties



3.3 Constraints on xSM parameters

xSM model parameters

$$v_s, \qquad m_{h_2}, \qquad \theta,$$

$$b_3, b_4.$$

Thermodynamics parameters

$$T_{\rm pt}, \quad \alpha, \quad \beta/H_n$$

Phenomenological parameters

$$\Omega_{\rm sw}(f) = \Omega_0 \left(\frac{f}{f_{\rm sw}}\right)^3 \left(\frac{7}{4+3\left(f/f_{\rm sw}\right)^2}\right)^{7/2}$$

$$\begin{split} V(H,S) &= -\mu^2 H^\dagger H + \lambda (H^\dagger H)^2 + \frac{a_1}{2} H^\dagger H S \\ &+ \frac{a_2}{2} H^\dagger H S^2 + \frac{b_2}{2} S^2 + \frac{b_3}{3} S^3 + \frac{b_4}{4} S^4, \end{split}$$

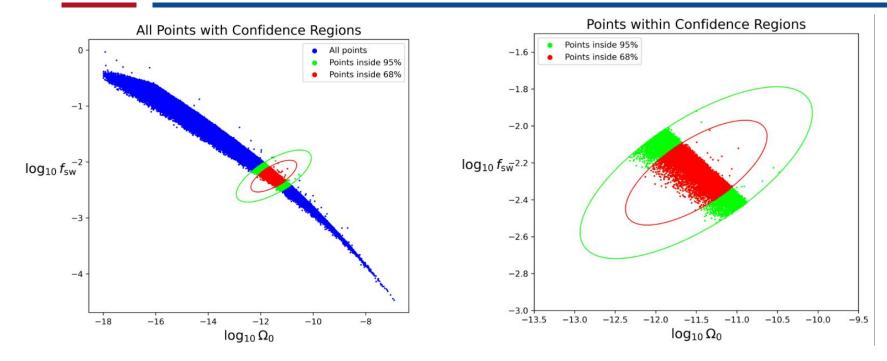
$$\Omega_{\rm sw}(f)h^2 = 2.65 \times 10^{-6} \left(\frac{H_{\rm pt}}{\beta}\right) \left(\frac{\kappa_{\rm sw}\alpha}{1+\alpha}\right)^2 \left(\frac{100}{g_*}\right)^{1/3}
\times v_{\rm w} \left(\frac{f}{f_{\rm sw}}\right)^3 \left(\frac{7}{4+3(f/f_{\rm sw})^2}\right)^{7/2} \Upsilon \left(\tau_{\rm sw}\right) ,$$

$$f_{\rm sw} = \frac{19}{v_{\rm w}} \left(\frac{\beta}{H_{\rm pt}}\right) \left(\frac{T_{\rm pt}}{100 {\rm GeV}}\right) \left(\frac{g_*}{100}\right)^{1/6} 10^{-6} {\rm Hz}$$

Alexandre Alves arXiv: 1812.09333



3.3 Constraints on xSM parameters

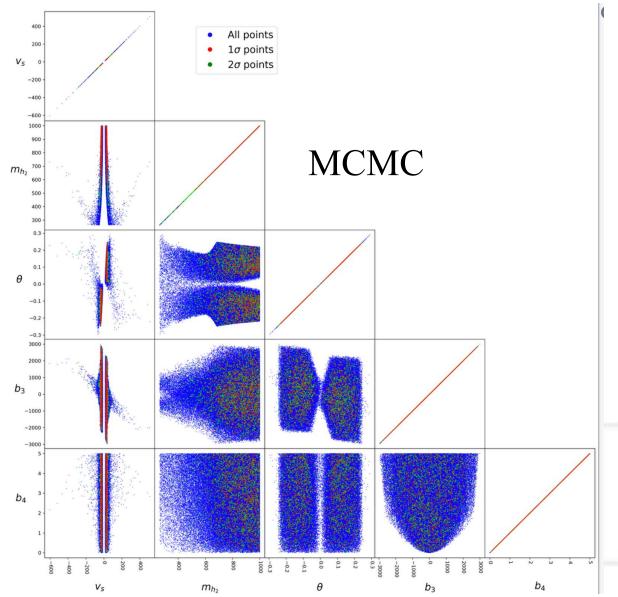


physical constraints Alexandre Alves arXiv: 1812.09333

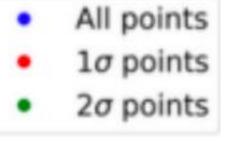
- 1. The Higgs potential must be stable and bounded from below.
- 2. Perturbativity and unitarity must hold at high energies.
- 3. Higgs couplings must remain close to the Standard Model values.



3.3 Constraints on xSM parameters



GWs observation significantly restricts the ranges of the xSM parameters and reveal strong parameter correlations, demonstrating it can directly constrain particle physics models beyond the Standard Model.



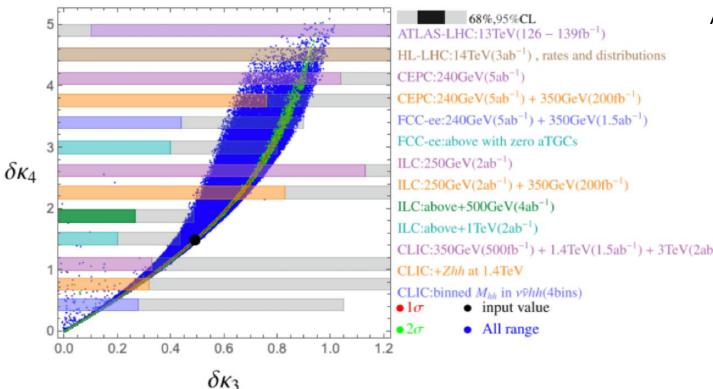


3.4 Constraints on Higgs couping parameters

$$\Delta \mathcal{L} = -\frac{1}{2} \frac{m_{h_1}^2}{v} (1 + \delta \kappa_3) h_1^2 - \frac{1}{8} \frac{m_{h_1}^2}{v^2} (1 + \delta \kappa_4) h_1^4.$$

$$\delta \kappa_3 = \theta^2 \left[-\frac{3}{2} + \frac{2m_{h_2}^2 - 2b_3 v_s - 4b_4 v_s^2}{m_{h_1}^2} \right] + \mathcal{O}(\theta^3)$$

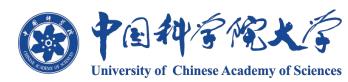
$$\delta \kappa_4 = \theta^2 \left[-3 + \frac{5m_{h_2}^2 - 4b_3 v_s - 8b_4 v_s^2}{m_{h_1}^2} \right] + \mathcal{O}(\theta^3)$$



Alexandre Alves arXiv: 1812.09333

collider-only measurements leave large uncertainties in here

GWs observations from FOPT provide complementary information that helps to narrow the allowed parameter space, highlighting its crucial role in probing the Higgs potential beyond the collider measurements.





4.1 Future improvement

- 1. Perform simulation in time-domain to capture realistic, nonstationary features.
- 2. Combine the space-based and ground-based detectors for joint observations.
- 3. Implement 2nd-generation TDI to improve laser noise cancellation.
- 4. Apply CLT and CG to reduce computation cost.
- 5. Explore more particle physics for GW predictions.



